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THE SIZE OF THE RISK SET UNDER RANDOM TRUNCATION



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THE SIZE OF THE RISK SET UNDER
RANDOM TRUNCATION

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THE SIZE OF THE RISK SET UNDER RANDOM TRUNCATION

SUMMARY

Let U^* and V^* be two independent positive random variables with continuous distribution functions F and G . Let (a_f, a_g) and (b_f, b_g) denote the lower and upper boundaries of (U^*, V^*) , respectively. Under left truncation, both U^* and V^* are observable only when $U^* \geq V^*$. Let $(U_1, V_1), \dots, (U_n, V_n)$ denote the truncated sample. Let $N_F(u) = \sum_{i=1}^n I_{[U_i \leq u]}$, $N_G(v) = \sum_{i=1}^n I_{[V_i \leq v]}$, and the size of the risk set $R_n(u) = N_G(u) - N_F(u-) = \sum_{i=1}^n I_{[V_i \leq u \leq U_i]}$, where $I_{[A]}$ is the indicator function of the event A . The nonparametric maximum likelihood estimate (NPMLE) of $F(x)$ and $G(x)$ are given by

$$\hat{F}_n(x) = 1 - \prod_{u \leq x} \left[1 - \frac{dN_F(u)}{R_n(u)} \right],$$

and

$$\hat{G}_n(x) = \prod_{v > x} \left[1 - \frac{dN_G(v)}{R_n(v)} \right],$$

where $dN_F(u) = N_F(u) - N_F(u-)$ and $dN_G(v) = N_G(v) - N_G(v-)$. Let $\mathcal{K} = \{(F, G) : F(0) = G(0) = 0, \alpha(F, G) > 0\}$, where $\alpha(F, G) = \int_0^\infty G(z) dF(z) = \int_0^\infty [1 - F(z)] dG(z)$. When $(F, G) \in \mathcal{K}$ and $a_f \geq a_g, b_f \geq b_g$, the consistency results for the estimate \hat{F}_n and \hat{G}_n were proved by Woodroffe (1985). Let $U_{(1)} < U_{(2)} < \dots < U_{(n)}$ denote the distinct ordered statistics of the sample U'_i 's. In applying $\hat{F}_n(x)$, a practical difficulty arises when $R_n(U_{(i)}) = 1$ for some $i \leq n-1$. Woodroffe (1985, Corollary 5) showed that when $(F, G) \in \mathcal{K}$, the probability $P(R_n(U_{(i)}) = 1$ for some $i \leq n-1$ converges to 0 as $n \rightarrow \infty$. In this note, we derive the exact probability of $P(R_n(U_{(1)}) = k)$ for $k = 1, \dots, n$ and give an alternative proof of $\lim_{n \rightarrow \infty} P(R_n(U_{(1)}) = k) = 0$ for $1 \leq k < \infty$. Simulation results indicate that the probability $P(R_n(U_{(1)}) = 1)$ can be significant when $a_f - a_g$ is not sufficiently large.

Key words: risk set; truncated data.

CHAPTER 1. INTRODUCTION

Let U^* and V^* be two independent positive random variables with continuous distribution functions F and G . Let (a_f, a_g) and (b_f, b_g) denote the lower and upper boundaries of (U^*, V^*) , respectively. Under left truncation, both U^* and V^* are observable only when $U^* \geq V^*$. Truncated data occur in astronomy, (e.g., Lynden-Bell (1971), Woodroffe (1985)), epidemiology, biometry (e.g., Wang, Jewell and Tsai (1986), Tsai, Jewell and Wang (1987)) and possibly in other field such as economics. The following examples describes situations where the models of left truncation are appropriate.

Example 1 (retirement data):

Channing House is a retirement center located in Palo Alto, California. Data on ages at death of 462 individuals (97 males and 365 females), who were in residence during the period January 1964 to July 1975, has been reported by Hyde (1980). The life lengths in this data set are left-truncated because an individual must survive to a sufficient age to enter the retirement community. The truncation variable V^* , is then the potential patient's age at entry, and the target variable U^* , is the patient's age at death. Obviously we can only observe (U^*, V^*) if $U^* \geq V^*$.

Example 2 (AIDS blood-transfusion data):

The blood transfusion related AIDS data given by Kalbfleisch and Lawless (1989). They gives infection times V^* , in months with 1 representing January 1978, incubation times T in months, and age in years for 34 'children' aged 0 to 4 years, 120 'adults' aged 5 to 59 years, and 141 'elderly' aged 60 and over, who were infected by contaminated blood transfusions and developed AIDS by 1 July 1986. Let $U^* = 102 - T$. The truncation effect comes from the fact that we only observed over the period $(0, 102]$. An individual is observed if and only if $T + V^* \leq 102$ or $V^* \leq U^*$.

Let $(U_1, V_1), \dots, (U_n, V_n)$ denote the truncated sample. Define

$$N_F(u) = \sum_{i=1}^n I_{[U_i \leq u]}, \quad N_G(v) = \sum_{i=1}^n I_{[V_i \leq v]}, \quad \text{and the size of the risk set } R_n(u) =$$

$N_G(u) - N_F(u-) = \sum_{i=1}^n I_{[V_i \leq u \leq U_i]}$, where $I_{[A]}$ is the indicator function of the event A . The nonparametric maximum likelihood estimate (NPMLE) of $F(x)$ and $G(x)$ (see Wang (1987)) are given by

$$\hat{F}_n(x) = 1 - \prod_{u \leq x} \left[1 - \frac{dN_F(u)}{R_n(u)} \right],$$

and

$$\hat{G}_n(x) = \prod_{v > x} \left[1 - \frac{dN_G(v)}{R_n(v)} \right],$$

where $dN_F(u) = N_F(u) - N_F(u-)$ and $dN_G(v) = N_G(v) - N_G(v-)$. Let $\mathcal{K} = \{(F, G) : F(0) = G(0) = 0, \alpha(F, G) > 0\}$, where $\alpha(F, G) = \int_0^\infty G(z) dF(z) = \int_0^\infty [1 - F(z)] dG(z)$. The justifications of using $\hat{F}_n(x)$ and $\hat{G}_n(x)$ are given as follows,

$$F^*(x) = P(U_i \leq x) = P(U^* \leq x | U^* \geq V^*) = P(V^* \leq U^* \leq x) / \alpha(F, G) = \int_0^x G(u) dF(u) = G(x) dF(x) / \alpha(F, G)$$

$$R(x) = P(V_i \leq x \leq U_i) = P(V^* \leq x \leq U^* | U^* \geq V^*) = [\alpha(F, G)]^{-1} G(x) [1 - F(x)]$$

$$\text{Hence, } \frac{dF^*(x)}{R_n(x)} = \frac{dF(x)}{1 - F(x)} = d\Lambda(x), \text{ where } \Lambda(x) = \int_0^x \frac{dF(u)}{1 - F(u)}$$

Note that

$$\begin{aligned} 1 - F(x) &= \prod_{u \leq x} \left[1 - d\Lambda(u) \right] \\ &= \prod_{u \leq x} \left[1 - \frac{dF(u)}{1 - F(u-)} \right] = \prod_{u \leq x} \left[1 - \frac{dF^*(u)}{R(u)} \right] \end{aligned}$$

Now $dF^*(u)$ can be consistently estimated by $\frac{dN_F(u)}{n} = \frac{N_F(u) - N_F(u-)}{n}$ and $R(u)$ can be consistently estimated by $\frac{R_n(u)}{n} = \frac{\sum_{i=1}^n I_{[V_i \leq u \leq U_i]}}{n}$. This justified the use of $\hat{F}_n(x)$ and $\hat{G}_n(x)$.

When $(F, G) \in \mathcal{K}$ and $a_f \geq a_g$ $b_f \geq b_g$, the consistency results for the estimate \hat{F}_n and \hat{G}_n were proved by Woodroffe (1985). Let $U_{(1)} < U_{(2)} < \dots < U_{(n)}$ denote

the distinct ordered statistics of the sample U_i 's. Note that $R_n(x)/n$ is a consistent estimator of $R(x) = [\alpha(F, G)]^{-1}G(x)[1 - F(x)]$. The $R(x)$ is not monotone in x and converge to zero if $G(x) \rightarrow 0$ or $F(x) \rightarrow 1$. Especially, in applying $F_n(x)$, a practical difficulty arises when $R_n(U_{(i)}) = 1$ for some $i \leq n - 1$. Since $R_n(U_{(i)}) = 1$ for some $i \leq n - 1$, then $F_n(U_{(i)}) = 1$. This is a disturbing property of the estimators. Furthermore, even when $R_n(U_{(i)}) > 1$ for all $i \leq n - 1$, \hat{F}_n may still be a very poor estimator (badly biased and large variance) of F for moderate sample sizes because of the small risk set size $R_n(x)$ for x near a_g (see Woodroffe 1985 Lemma 2, and a simulation study of Lai and Ying (1991, pages 440-441).

Woodroffe (1985, Corollary 5) showed that when $(F, G) \in \mathcal{K}$,

- (i) $P(R_n(U_{(i)}) = 1 \text{ for some } i \leq n - 1)$ converges to 0 as $n \rightarrow \infty$ and
- (ii) $\min\{R_n(U_{(i)}) : 1 \leq i \leq (1-\epsilon)n\} \rightarrow \infty$ in probability as $n \rightarrow \infty$ for all ϵ , $0 < \epsilon < 1$.

The proof of the second assertion (ii) is given by Woodroffe (1985, page 172). The proof of the first assertion is only briefly described by Woodroffe (1985). We now give the detailed proof of the first assertion.

proof of the first assertion:

First, we show that $R_n(U_{(i)}) = 1$ implies that $R_n(V_{(i+1)}) = 1$, where $V_{(i+1)}$ denote the $(i + 1)^{th}$ order statistic of the sample V_i 's. Note that

$$\sum_{j=1}^n I_{[V_j \leq U_{(i)} \leq U_j]} = \sum_{j=i}^n I_{[\tilde{V}_{(j)} \leq U_{(i)} \leq U_{(j)}]}, \quad (1.1)$$

where $\tilde{V}_{(j)}$ is the concomitant of $U_{(j)}$. Hence, (1.1) = 1 implies that $U_{(i)} < \tilde{V}_{(j)}$ for $j = i + 1, \dots, n$ and $U_{(i)} > \tilde{V}_{(j)}$ for $j = 1, \dots, i - 1$. Hence, $V_{(i+1)} = \tilde{V}_{(k)}$ for some $k \in \{j = i + 1, \dots, n\}$. Thus, we have

$$\begin{aligned} \sum_{j=1}^n I_{[\tilde{V}_{(j)} \leq V_{(i+1)} \leq U_{(j)}]} &= \sum_{j=1}^n I_{[\tilde{V}_{(j)} \leq \tilde{V}_{(k)} \leq U_{(j)}]} \\ &= \sum_{j=1}^i I_{[\tilde{V}_{(j)} \leq \tilde{V}_{(k)} \leq U_{(j)}]} + I_{[\tilde{V}_{(k)} \leq \tilde{V}_{(k)} \leq U_{(k)}]} = 0 + 1 = 1 \end{aligned}$$

Now, Let $X_j = 1/U_j$ and $Y_j = 1/V_j$. Hence, we have

$$\begin{aligned} R_n(U_{(i)}) &= R_n(V_{(i+1)}) = \sum_{j=1}^n I_{[V_j \leq V_{(i+1)} \leq U_j]} \\ &= \sum_{j=1}^n I_{[\frac{1}{U_j} \leq \frac{1}{V_{(i+1)}} \leq \frac{1}{V_j}]} = \sum_{j=1}^n I_{[X_j \leq \frac{1}{V_{(i+1)}} \leq Y_j]} \\ &= \sum_{j=1}^n I_{[X_j \leq Y_{(n-i)} \leq Y_j]}. \end{aligned}$$

Hence, $R_n(U_{(i)}) = 1$ for $i = 1, \dots, n-1$ is equivalent to $R_n(Y_{(n-i)}) = 1$ for $i = 1, \dots, n-1$. The first assertion then follows from the second assertion by letting $\epsilon = 1/n$.

For randomly censored data, Maller and Zhou (1993) gave necessary and sufficient conditions for the probability that the largest censored data is zero. Note that the Kaplan-Meier estimator (1958) for the survival function of randomly censored time-to-event data is improper when the largest observation is censored. In this note, we derive the exact probability of $P(R_n(U_{(1)}) = k)$ for $k = 1, \dots, n$. Motivated by Maller and Zhou (1993) we give an alternative proof of $\lim_{n \rightarrow \infty} P(R_n(U_{(1)}) = k) = 0$ for $1 \leq k < \infty$. Simulation results indicate that the probability $P(R_n(U_{(1)}) = 1)$ can be significant when $a_f - a_g$ is not sufficiently large.

CHAPTER 2. THE PROBABILITY $P(R_n(U_{(1)}) = k)$

The following Lemma derives the exact probability $P(R_n(U_{(1)}) = k)$

Lemma 2.1:

For $k = 1, \dots, n$,

$$P(R_n(U_{(1)}) = k) = \int_{\max\{a_f, a_g\}}^{b_f} P(B(x) = k - 1) dF_{U_{(1)}}(x),$$

where $B(x)$ is binomial random variable with parameter $n - 1$ and the probability of success $p(x) = P(V_i < x < U_i)/P(U_i > x) = P(V^* < x < U^*)/P(U^* > x, U^* > V^*)$, and $F_{U_{(1)}}(x) = P(U_{(1)} \leq x) = [P(U_i \leq x)]^n = [P(U^* \leq x | U^* \geq V^*)]^n$.

proof:

Let F_u and G_v denote the distribution function of U_i and V_i , respectively. That is, $F_u(x) = P(U_i \leq x) = P(U^* \leq x | U^* \geq V^*)$ and $G_v(x) = P(V_i \leq x) = P(V^* \leq x | U^* \geq V^*)$. For $j = 1, \dots, n$, let $D_j = \{(U_i, V_i) : i = 1, \dots, j - 1, j + 1, \dots, n\}$ denote the set of the observations when $U_{(j)}$ is deleted from the sample. Given $k = 1, \dots, n$,

$$\begin{aligned} P(R_n(U_{(1)}) = k) &= \\ &= \sum_{j=1}^n P(U_j < \min_{s \in D_j} U_s, \max_{s=i_1, \dots, i_{k-1}} V_s < U_j < \min_{s \in D_j, s \neq i_1, \dots, i_{k-1}} V_s, \text{ for } i_1, \dots, i_{k-1} \in D_j) \\ &= nP(\max_{s=i_1, \dots, i_{k-1}} V_s < U_1 < \min_{s=i_1, \dots, i_{k-1}} U_s, U_1 < \min_{s \in D_1, s \neq i_1, \dots, i_{k-1}} V_s, \text{ for } i_1, \dots, i_{k-1} \in D_1) \\ &= n \binom{n-1}{k-1} \int_{\max\{a_f, a_g\}}^{b_f} [P(V_i < x < U_i)]^{k-1} [P(V_i > x)]^{n-k} dF_u(x) \\ &= \int_{\max\{a_f, a_g\}}^{b_f} \binom{n-1}{k-1} \left[\frac{P(V_i < x < U_i)}{P(U_i > x)} \right]^{k-1} \left[\frac{P(V_i > x)}{P(U_i > x)} \right]^{n-k} n [P(U_i > x)]^{n-1} dF_u(x). \end{aligned} \tag{2.1}$$

Since $P(V_i > x) = P(U_i > V_i > x)$, we have $P(V_i > x)/P(U_i > x) = P(V_i > x | U_i > x) = 1 - P(V_i < x | U_i > x)$

$= 1 - P(V_i < x < U_i)/P(U_i > x)$. Note that $n[P(U_i > x)]^{n-1}dF_u(x) = dF_{U_{(1)}}(x)$, where $F_{U_{(1)}}(x) = P(U_{(1)} \leq x)$. Hence, (2.1) can be expressed as

$$\begin{aligned} & \int_{\max\{a_f, a_g\}}^{b_f} \binom{n-1}{k-1} [p(x)]^{k-1} [1-p(x)]^{n-k} dF_{U_{(1)}}(x) \\ &= \int_{\max\{a_f, a_g\}}^{b_f} P(B(x) = k-1) dF_{U_{(1)}}(x). \end{aligned}$$

The proof is completed.

The following Lemma shows that $\lim_{n \rightarrow \infty} P(R_n(U_{(1)}) = k) = 0$ for $1 \leq k < \infty$.

Lemma 2.2:

Suppose that $(F, G) \in \mathcal{K}$ then $\lim_{n \rightarrow \infty} P(R_n(U_{(1)}) = k) = 0$ for $1 \leq k < \infty$.

proof:

First, we consider the case $a_f > a_g$ and $k = 1$. Note that $a_f > a_g$ implies that $\alpha(F, G) > 0$. From Lemma 2.1, when $a_f > a_g$, we obtain

$$P(R_n(U_{(1)}) = 1) = n \int_{a_f}^{b_f} [P(V_i > x)]^{n-1} dF_u(x) \leq n[P(V_i > a_f)]^{n-1}.$$

Since $P(V_i > a_f) < 1$, we have $n[P(V_i > a_f)]^{n-1} \rightarrow 0$, as $n \rightarrow \infty$. the proof is completed.

Next, we consider the case $a_f \leq a_g$.

Define $\tilde{U}_i = b_f - U_i$ and $\tilde{V}_i = b_f - V_i$. Let F_1 and F_2 denote the distribution function of \tilde{V}_i and \tilde{U}_i . When $a_f \leq a_g$, $P(R_n(U_{(1)}) = 1)$ can be written as

$$P(R_n(U_{(1)}) = 1) = n \int_0^{b_f - a_g} [F_1(x)]^{n-1} dF_2(x)$$

Since $F_1(x) < 1$ for $x < b_f - a_g$, according to Lemma 2.3 of Maller and Zhou (1993),

$$\lim_{n \rightarrow \infty} n \int_0^{b_f - a_g} [F_1(x)]^{n-1} dF_2(x) = L \text{ if and only if } \lim_{x \uparrow b_f - a_g} \frac{1 - F_2(x)}{1 - F_1(x)} = L.$$

This is equivalent to

$$\lim_{x \downarrow a_g} \frac{F_u(x)}{G_v(x)} = \lim_{x \downarrow a_g} \frac{\int_{a_g}^x G(z) dF(z)}{\int_{a_g}^x G(z) dF(z) + G(x) \bar{F}(x)} = \frac{1}{1 + \frac{G(x) \bar{F}(x)}{\int_{a_g}^x G(z) dF(z)}} = L.$$

Note that

$$\frac{G(x) \bar{F}(x)}{\int_{a_g}^x G(z) dF(z)} = \frac{\bar{F}(x)}{\int_{a_g}^x \frac{G(z)}{G(x)} dF(z)} \geq \frac{\bar{F}(x)}{\int_{a_g}^x dF(z)} = \frac{\bar{F}(x)}{F(x) - F(a_g)}.$$

Since $\lim_{x \downarrow a_g} F(x) - F(a_g) = 0$ and $\lim_{x \downarrow a_g} \bar{F}(x) = \bar{F}(a_g) > 0$, we have

$$\lim_{x \downarrow a_g} \frac{F_u(x)}{G_v(x)} = 0.$$

Hence, $\lim_{n \rightarrow \infty} P(R_n(U_{(1)}) = 1) = 0$.

Next, we consider the case $k > 1$. From Lemma 2.1, we have

$$\begin{aligned} P(R_n(U_{(1)}) = k) &= n \binom{n-1}{k-1} \int_{\max\{a_f, a_g\}}^{b_f} [P(V_i < x < U_i)]^{k-1} [P(V_i > x)]^{n-k} dF_u(x) \\ &\leq n \binom{n-1}{k-1} \int_{\max\{a_f, a_g\}}^{b_f} [1 - F_u(x)]^{k-1} [1 - G_v(x)]^{n-k} dF_u(x) \\ &= n \binom{n-1}{k-1} \int_{\max\{a_f, a_g\}}^{b_f} [F_2(b_f - x)]^{k-1} [F_1(b_f - x)]^{n-k} dF_2(b_f - x) \\ &= n \binom{n-1}{k-1} \int_0^{b_f - \max\{a_f, a_g\}} [F_2(y)]^{k-1} [F_1(y)]^{n-k} dF_2(y). \end{aligned}$$

Since $F_1(x) < 1$ for $x < b_f - \max\{a_f, a_g\}$, according to (2.9) and (2.10) of Maller and Zhou (1993),

$$\lim_{n \rightarrow \infty} n \binom{n-1}{k-1} \int_0^{b_f - \max\{a_f, a_g\}} [F_2(y)]^{k-1} [F_1(y)]^{n-k} dF_2(y) = L^k$$

if and only if

$$\lim_{x \uparrow b_f - \max\{a_f, a_g\}} \frac{1 - F_2(x)}{1 - F_1(x)} = L.$$

This is equivalent to $\lim_{x \downarrow \max\{a_f, a_g\}} \frac{F_u(x)}{G_v(x)} = L$. Similar to the argument for $k = 1$, we have $\lim_{x \downarrow \max\{a_f, a_g\}} F(x) - F(\max\{a_f, a_g\}) = 0$ and $\lim_{x \downarrow \max\{a_f, a_g\}} \bar{F}(x) = \bar{F}(\max\{a_f, a_g\}) > 0$. The proof is completed.

From Lemma 2.1,

$$P(R_n(U_{(1)}) = 1) = n \int_{\max\{a_f, a_g\}}^{b_f} [P(V_i > x)]^{n-1} dF_u(x) \leq n [P(V_i > \max\{a_f, a_g\})]^{n-1}.$$

Hence, when $a_f > a_g$ and $[P(V_i > a_f)]^{n-1}$ is sufficiently small, the probability $P(R_n(U_{(1)}) = 1)$ is negligible. However, when $a_f \leq a_g$, this probability can be significant. Similarly, for $k > 1$,

$$\begin{aligned} P(R_n(U_{(1)}) = k) &\leq n \binom{n-1}{k-1} \int_{\max\{a_f, a_g\}}^{b_f} [P(V_i > x)]^{n-k} dF_u(x) \\ &\leq n \binom{n-1}{k-1} [P(V_i > \max\{a_f, a_g\})]^{n-k}. \end{aligned}$$

Hence, for small values of k , when $a_f \leq a_g$, this probability can be significant.

CHAPTER 3. SIMULAITON RESULTS AND DISCUSSION

Next, simulation study was conducted to investigate the probability

$P(R_n(U_{(1)}) = 1)$. The U^* 's are left-truncated Weibull distributed:

$U^* \sim LW(a_f, \delta)$, that is $F(x) = 1 - e^{-(x-a_f)^\delta}$ for $x \geq a_f$ with varying parameters $a_f = 0.3(0.3)0.9$ and $\delta = 0.25, 1.0, 4.0$. The V^* 's are uniform distributed: $V^* \sim U(a_g, \delta_g)$ with $a_g = 0.5$ and $b_g = 5.0$. Sample sizes are chosen as $n = 10, 25$ and 50 . The replication is 10000 times. Table 1 lists the probability $P(R_n(U_{(1)}) = 1)$.

Table 1. Simulation results of $P(R_n(U_{(1)}) = 1): V_i \sim U(0.5, 5.0)$

n	δ	$a_f = 0.3$	$a_f = 0.6$	$a_f = 0.9$
10	0.25	0.105	0.248	0.117
25	0.25	0.049	0.141	0.005
50	0.25	0.037	0.050	0.000
10	1.00	0.098	0.071	0.018
25	1.00	0.033	0.014	0.000
50	1.00	0.018	0.002	0.000
10	4.00	0.015	0.002	0.000
25	4.00	0.003	0.000	0.000
50	4.00	0.001	0.000	0.000

Simulation results indicate that when $n = 50$ or ($n = 25$ and $a_f - a_g = 0.6$), the probability $P(R_n(U_{(1)}) = 1)$ is close to zero. However, when $n = 10$, $a_f - a_g = -0.2, 0.1$ and $\delta = 0.25, 1$, the probability is larger than 0.05. Lai and Ying (1991) suggest a solution to this problem by a slight modification of the NPMLE \hat{F}_n where deaths are ignored when the risk set is small. Their estimator is given by

$$\tilde{F}_n(x) = 1 - \prod_{u \leq x} \left[1 - I_{[R_n(u) \geq cn^p]} \frac{dN_F(u)}{R_n(u)} \right],$$

where $c > 0$ and $0 < p < 1$. This estimator $\tilde{F}_n(u)$ is asymptotically equivalent to the NPMLE \hat{F}_n . For finite sample, further investigation is needed to compare the two estimators.

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